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DATA STRUCTURES AND ALGORITHMS

The contents in this E material are from

Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed "Fundamentals of Data Structures in C", Computer Science Press, 1992.



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- Linear list.
- One end is called top.
- Other end is called **bottom**.
- Additions to and removals from the top end only.

Stack Of Cups



- Add a cup to the stack.
- Remove a cup from new stack.
- A stack is a LIFO list.

Parentheses Matching

- (((a+b)*c+d-e)/(f+g)-(h+j)*(k-l))/(m-n)
 - Output pairs (u,v) such that the left parenthesis at position u is matched with the right parenthesis at v.
 - (2,6) (1,13) (15,19) (21,25) (27,31) (0,32) (34,38)
- (a+b))*((c+d)
 - (0,4)
 - right parenthesis at 5 has no matching left parenthesis
 - (8,12)
 - left parenthesis at 7 has no matching right parenthesis

Parentheses Matching

- scan expression from left to right
- when a left parenthesis is encountered, add its position to the stack
- when a right parenthesis is encountered, remove matching position from stack









• (((a+b)*c+d-e)/(f+g)-(h+j)*(k-l))/(m-n)



• and so on

- Standard operations:
 - IsEmpty ... return true iff stack is empty
 - IsFull ... return true iff stack has no remaining capacity
 - Top ... return top element of stack
 - Push ... add an element to the top of the stack
 - Pop ... delete the top element of the stack

- Use a 1D array to represent a stack.
- Stack elements are stored in stack[0] through stack[top].



- stack top is at element e
- IsEmpty() => check whether top >= 0
 - **O**(1) time
- -IsFull() => check whether top == capacity 1
 - **O**(1) time
- Top() => If not empty return stack[top]
 - O(1) time

- Push(theElement) => if full then either error or increase capacity and then add at stack[top+1]
- Suppose we increase capacity when full
- -O(capacity) time when full; otherwise O(1)
- -Pop() => if not empty, delete from stack[top]
- -O(1) time

Push



void push(element item)
{/* add an item to the global stack */
 if (top >= MAX_STACK_SIZE - 1)
 StackFull();
 /* add at stack top */
 stack[++top] = item;

Pop



element pop()

{

}

if (top == -1)
 return StackEmpty();
return stack[top--];

StackFull()

void StackFull() { fprintf(stderr, "Stack is full, cannot add element."); exit(EXIT_FAILURE); }

StackFull()/Dynamic Array

- Use a variable called *capacity* in place of MAX_STACK_SIZE
- Initialize this variable to (say) 1
- When stack is full, double the capacity using REALLOC
- This is called array doubling

StackFull()/Dynamic Array

void StackFull()

{

REALLOC(stack, 2*capacity*sizeof(*stack); capacity *= 2;

Complexity Of Array Doubling

- Let final value of capacity be 2^k
- Number of pushes is at least $2^{k-1}+1$
- Total time spent on array doubling is $\Sigma_{1 \le i=k} 2^i$
- This is O(2^k)
- So, although the time for an individual push is O(capacity), the time for all n pushes remains O(n)!



- Linear list.
- One end is called front.
- Other end is called rear.
- Additions are done at the rear only.
- Removals are made from the front only.



front





¢___









front











front







front



Revisit Of Stack Applications

- Applications in which the stack cannot be replaced with a queue.
 - Parentheses matching.
 - Towers of Hanoi.
 - Switchbox routing.
 - Method invocation and return.
 - Try-catch-throw implementation.
- Application in which the stack may be replaced with a queue.
 - Rat in a maze.
 - Results in finding shortest path to exit.

Wire Routing





Label all reachable squares 1 unit from start.



Label all reachable unlabeled squares 2 units from start.



Label all reachable unlabeled squares 3 units from start.



Label all reachable unlabeled squares 4 units from start.





Label all reachable unlabeled squares 5 units from start.





Label all reachable unlabeled squares 6 units from start.





End pin reached. Traceback.





End pin reached. Traceback.
Queue Operations

- IsFullQ ... return true iff queue is full
- IsEmptyQ ... return true iff queue is empty
- $AddQ \dots add$ an element at the rear of the queue
- DeleteQ ... delete and return the front element of the queue

Queue in an Array

- Use a 1D array to represent a queue.
- Suppose queue elements are stored with the front element in queue[0], the next in queue[1], and so on.



- DeleteQ() => delete queue[0]
 - O(queue size) time
- AddQ(x) => if there is capacity, add at right end -O(1) time

O(1) AddQ and DeleteQ

- to perform each opertion in O(1) time (excluding array doubling), we use a circular representation.

• Use a 1D array queue.



• Circular view of array.



• Possible configuration with 3 elements.



• Another possible configuration with 3 elements.



- Use integer variables front and rear.
 - front is one position counterclockwise from first element
 - rear gives position of last element



Add An Element

• Move rear one clockwise.



Add An Element

- Move rear one clockwise.
- Then put into queue[rear].



Delete An Element

• Move front one clockwise.



Delete An Element

- Move front one clockwise.
- Then extract from queue[front].



Moving rear Clockwise

• rear++;

if (rear = capacity) rear = 0;



• rear = (rear + 1) % capacity;









- When a series of removes causes the queue to become empty, front = rear.
- When a queue is constructed, it is empty.
- So initialize front = rear = 0.









- When a series of adds causes the queue to become full, front = rear.
- So we cannot distinguish between a full queue and an empty queue!

Ouch!!!!!

- Remedies.
 - Don't let the queue get full.
 - When the addition of an element will cause the queue to be full, increase array size.
 - This is what the text does.
 - Define a boolean variable lastOperationIsAddQ.
 - Following each AddQ set this variable to true.
 - Following each **DeleteQ** set to false.
 - Queue is empty iff (front == rear) && !lastOperationIsAddQ
 - Queue is full iff (front == rear) && lastOperationIsAddQ

Ouch!!!!!

- Remedies (continued).
 - Define an integer variable size.
 - Following each AddQ do size++.
 - Following each DeleteQ do size--.
 - Queue is empty iff (size == 0)
 - Queue is full iff (size == arrayLength)
 - Performance is slightly better when first strategy is used.



Priority Queues



Two kinds of priority queues:

- Min priority queue.
- Max priority queue.

Min Priority Queue

- Collection of elements.
- Each element has a priority or key.
- Supports following operations:
 - empty
 - size
 - insert an element into the priority queue (push)
 - get element with min priority (top)
 - remove element with min priority (pop)

Max Priority Queue

- Collection of elements.
- Each element has a priority or key.
- Supports following operations:
 - empty
 - size
 - insert an element into the priority queue (push)
 - get element with max priority (top)
 - remove element with max priority (pop)

Complexity Of Operations

Use a heap or a leftist tree (both are defined later).

empty, size, and top $\Rightarrow O(1)$ time

insert (push) and remove (pop) => O(log n)
time where n is the size of the priority
queue

Applications

Sorting

- use element key as priority
- insert elements to be sorted into a priority queue
- remove/pop elements in priority order
 - if a min priority queue is used, elements are extracted in ascending order of priority (or key)
 - if a max priority queue is used, elements are extracted in descending order of priority (or key)

Sorting Example

Sort five elements whose keys are 6, 8, 2, 4, 1 using a max priority queue.

- Insert the five elements into a max priority queue.
- Do five remove max operations placing removed elements into the sorted array from right to left.

After Inserting Into Max Priority Queue



After First Remove Max Operation



After Second Remove Max Operation





After Third Remove Max Operation





After Fourth Remove Max Operation



2	4	6	8
---	---	---	---

After Fifth Remove Max Operation



1	2 4	6	8
---	-----	---	---







• list elements are stored, in memory, in an arbitrary order

 explicit information (called a link) is used to go from one element to the next
Memory Layout

Layout of L = (a,b,c,d,e) using an array representation.



A linked representation uses an arbitrary layout.



Linked Representation





use a variable first to get to the first element a

Normal Way To Draw A Linked List





link or pointer field of node

data field of node



- •A chain is a linked list in which each node represents one element.
- There is a link or pointer from one element to the next.
- The last node has a NULL (or 0) pointer.

Node Representation

typedef struct listNode *listPointer; typedef struct { char data; listPointer link;

} listNode;

link data

get(0)



desiredNode = first; // gets you to first node
return desiredNode->data;





desiredNode = first->link; // gets you to second node
return desiredNode->data;





desiredNode = first->link->link; // gets you to third node
return desiredNode->data;



Delete An Element

first a b c d e

delete(0)

deleteNode = first; first = first->link; free(deleteNode);

delete(2)



beforeNode = first->link;

delete(2)



save pointer to node that will be deleted deleteNode = beforeNode->link;

delete(2)



now change pointer in **beforeNode**

beforeNode->link = beforeNode->link->link;
free(deleteNode);

insert(0,'f')



Step 1: get a node, set its data and link fields

MALLOC(newNode, sizeof(*newNode)); newNode->data = 'f'; newNode->link = NULL;

insert(0,'f')



Step 2: update first

first = newNode;



- first find node whose index is 2
- next create a new node and set its data and link fields
- finally link beforeNode to newNode



- beforeNode = first->link->link;
- MALLOC(newNode, sizeof(*newNode));
- newNode->data = 'f';
- newNode->link = beforeNode->link;
- beforeNode->link = newNode;

Solution Chain With Header Node









Circular List









firstNode







Empty Doubly Linked Circular List With Header Node





