

### UNIT-III

#### Expectation:

Definition: - Let  $X$  be a r.v. with pdf (p.m.f)  $f(x)$ .

Then its mathematical expectation, is given by

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx \quad \text{for continuous r.v.}$$

$$= \sum_x x f(x) \quad \text{for discrete r.v.}$$

provided the RHS integral (or) series is absolutely convergent.

$$\text{i.e., } \int_{-\infty}^{\infty} |x| f(x) dx < \infty \quad (\text{or}) \quad \sum_x |x| f(x) < \infty.$$

Expectation of a function of a R.V.

Let  $X$  be a r.v. with pdf (p.m.f)  $f(x)$  and D.F  $F(x)$ .  
If  $g(\cdot)$  is a function  $\rightarrow g(x)$  is a r.v. and  $E[g(x)]$  exists,  
then the expectation of the function  $g(x)$  is given by

$$E[g(x)] = \int_{-\infty}^{\infty} g(x) f(x) dx = \int_{-\infty}^{\infty} g(x) f(x) dx \quad \left\{ \begin{array}{l} \text{for continuous} \\ \text{case} \end{array} \right.$$

$$= \sum_x g(x) f(x) \quad \text{for discrete case}$$

$$\text{By defn } E[g(x)] = E(Y) = \int y dH_y(y) \quad \text{where } Y = g(x)$$

$$= \int y h(y) dy \quad (\text{for continuous case})$$

$$= \sum y h(y) \quad (\text{for discrete case}).$$

Note:

If  $g(x) = x^r$  ( $r$ : +ve integer),

$$\text{then } E(x^r) = \int_{-\infty}^{\infty} x^r f(x) dx = \mu_r' \quad \text{the } r^{\text{th}} \text{ moment about origin.}$$

$$\text{If } r=1, \quad E(x) = \int x f(x) dx = \mu_1' = \text{Mean}$$

$$\text{If } r=2, \quad E(x^2) = \int x^2 f(x) dx = \mu_2'$$

$$\text{and } \mu_2 = \mu_2' - (\mu_1')^2 = E(x^2) - [E(x)]^2 = \text{Variance of } x.$$

1) Addition Theorem on Expectation:  
 For 2 variables:  
 If  $X$  &  $Y$  be continuous r.v's with joint then  

$$E(X+Y) = E(X) + E(Y)$$
 provided all the Expectations exist.

For 'n' variables:  
 If  $X_1, X_2, \dots, X_n$  are random variables then  

$$E(X_1 + X_2 + \dots + X_n) = E(X_1) + E(X_2) + \dots + E(X_n)$$
 if all the expectation exist.

2) Multiplication Theorem on Expectation:

For 2 variables:- independent  
 If  $X$  &  $Y$  be two r.v's, then  $E(XY) = E(X) \cdot E(Y)$ .

For 'n' variables:  
 If  $X_1, X_2, \dots, X_n$  are 'n' independent r.v's, then  

$$E(X_1 \cdot X_2 \cdot \dots \cdot X_n) = E(X_1) \cdot E(X_2) \cdot \dots \cdot E(X_n)$$
 provided all the Expectations exist.

3) If  $X$  is a r.v and  $a$  is a constant, then

i)  $E[a \cdot \psi(X)] = a \cdot E[\psi(X)]$

ii)  $E[\psi(X) + a] = E[\psi(X)] + a$

where  $\psi(X)$  is a function of  $X$ ,  
 and if all the Expectations exist.

4) If  $X$  is a r.v and  $a$  &  $b$  are constants, then

$$E(aX + b) = a \cdot E(X) + b$$

5) Let  $X_1, X_2, \dots, X_n$  be any 'n' r.v's and  
 if  $a_1, a_2, \dots, a_n$  are constants then

$$E\left(\sum_{i=1}^n a_i X_i\right) = \sum_{i=1}^n a_i E(X_i)$$

6) If  $X \geq 0$  and  $Y \geq 0$  are two r.v's then

i)  $E(X) \geq 0$

ii)  $E(Y) \leq E(X)$  if  $Y \leq X$

iii)  $|E(X)| \leq E|X|$ .

7) If  $\mu_r'$  exists, then  $\mu_r''$  exists for all  $1 \leq r \leq r$ .

i.e., if  $E(X^r) < \infty$ , then  $E(X^{r+1})$  exists  $\forall 1 \leq r \leq r$ .

8) If  $X$  is a r.v., then  $V(aX+b) = a^2 V(X)$   
where  $a$  &  $b$  are constants.

9) Covariance:

If  $X$  &  $Y$  are two r.v.'s and  $a$  &  $b$  are constants, then

i) Covariance between  $X$  &  $Y$  is defined as

$$\begin{aligned} \text{Cov}(X, Y) &= E\left[\{X - E(X)\}\{Y - E(Y)\}\right] \\ &= E(XY) - E(X) \cdot E(Y) \quad \text{if } X \text{ \& } Y \text{ are not independent} \end{aligned}$$

$$= 0 \quad \text{if } X \text{ \& } Y \text{ are independent} \\ \text{i.e. } E(XY) = E(X) \cdot E(Y).$$

ii)  $\text{Cov}(X+a, Y+b) = \text{Cov}(X, Y)$

iii)  $\text{Cov}(aX, bY) = ab \text{Cov}(X, Y)$

iv)  $\text{Cov}\left(\frac{X-\bar{X}}{\sigma_X}, \frac{Y-\bar{Y}}{\sigma_Y}\right) = \frac{1}{\sigma_X \sigma_Y} \text{Cov}(X, Y).$

v)  $\text{Cov}(aX+b, cY+d) = a \cdot c \text{Cov}(X, Y)$  where  $c$  &  $d$  are constants

vi)  $\text{Cov}(X+Y, Z) = \text{Cov}(X, Z) + \text{Cov}(Y, Z)$   
where  $Z$  is also a r.v.

vii)  $\text{Cov}(aX+bY, cX+dY) =$   
 $= ac\sigma_X^2 + bd\sigma_Y^2 + (ad+bc)\text{Cov}(X, Y).$

10) Correlation Coefficient:

The correlation coefficient between  $X$  &  $Y$  is

$$\begin{aligned} \rho_{XY} &= \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y} = \frac{E\left[\{X - E(X)\}\{Y - E(Y)\}\right]}{E\left[\{X - E(X)\}^2\right]^{1/2} E\left[\{Y - E(Y)\}^2\right]^{1/2}} \\ &= \frac{E(XY) - E(X) \cdot E(Y)}{\sigma_X \sigma_Y}. \end{aligned}$$

ii) If  $X$  &  $Y$  are independent r.v.'s then

$$E[h(X) \cdot k(Y)] = E[h(X)] \cdot E[k(Y)]$$

where  $h(\cdot)$  is a function of  $X$  alone  
&  $k(\cdot)$  is a function of  $Y$  alone  
provided all the expectations exist.

Source: Fundamentals of Mathematical Statistics by V. K. Kapoor & S. C. Gupta

## Conditional Expectation

**Discrete Case.** The conditional expectation or mean value of a continuous function  $g(X, Y)$  given that  $Y = y_j$ , is defined by

$$E\{g(X, Y) | Y = y_j\} = \frac{\sum_{i=1}^{\infty} g(x_i, y_j) P(X = x_i | Y = y_j)}{\sum_{i=1}^{\infty} g(x_i, y_j) P(X = x_i \cap Y = y_j)} = \frac{\sum_{i=1}^{\infty} g(x_i, y_j) P(X = x_i | Y = y_j)}{P(Y = y_j)} \quad \dots(6.46)$$

i.e.,  $E[g(X, Y) | Y = y_j]$  is nothing but the expectation of the function  $g(X, y_j)$  of  $X$  w.r.t. the conditional distribution of  $X$  when  $Y = y_j$ .

In particular, the conditional expectation of a discrete random variable  $X$  given  $Y = y_j$  is

$$E(X | Y = y_j) = \sum_{i=1}^{\infty} x_i P(X = x_i | Y = y_j) \quad \dots(6.47)$$

The conditional variance of  $X$  given  $Y = y_j$  is likewise given by

$$V(X | Y = y_j) = E\{[X - E(X | Y = y_j)]^2 | Y = y_j\} \quad \dots(6.47a)$$

The conditional expectation of  $g(X, Y)$  and the conditional variance of  $Y$  given  $X = x_i$  may also be defined in an exactly similar manner.

**Continuous Case.** The conditional expectation of  $g(X, Y)$  on the hypothesis  $Y = y$  is defined by

$$E\{g(X, Y) | Y = y\} = \frac{\int_{-\infty}^{\infty} g(x, y) f_{X|Y}(x | y) dx}{\int_{-\infty}^{\infty} g(x, y) f(x, y) dx} = \frac{\int_{-\infty}^{\infty} g(x, y) f(x, y) dx}{f_Y(y)} \quad \dots(6.48)$$

In particular, the conditional mean of  $X$  given  $Y = y$  is defined by

$$E(X | Y = y) = \frac{\int_{-\infty}^{\infty} x f(x, y) dx}{f_Y(y)}$$

Similarly, we define

$$E(Y | X = x) = \frac{\int_{-\infty}^{\infty} y f(x, y) dy}{f_X(x)} \quad \dots(6.48 a)$$

The conditional variance of  $X$  may be defined as

$$V(X | Y = y) = E\left\{[X - E(X | Y = y)]^2 | Y = y\right\}$$

Similarly, we define

$$V(Y | X = x) = E\left\{[Y - E(Y | X = x)]^2 | X = x\right\} \quad \dots(6.49)$$

**Theorem 6.13.** The expected value of  $X$  is equal to the expectation of the conditional expectation of  $X$  given  $Y$ . Symbolically,

$$E(X) = E[E(X|Y)] \quad \dots(6.50)$$

[Calicut Univ. B.Sc. (Main Stat.), 1980]

**Proof.**  $E[E(X|Y)] = E\left[\sum_i x_i P(X = x_i | Y = y_j)\right]$

$$\begin{aligned} &= E\left[\sum_i x_i \frac{P(X = x_i \cap Y = y_j)}{P(Y = y_j)}\right] \\ &= \sum_j \left[ \sum_i \left\{ x_i \frac{P(X = x_i \cap Y = y_j)}{P(Y = y_j)} \right\} \right] P(Y = y_j) \\ &= \sum_j \sum_i x_i \cdot P(X = x_i \cap Y = y_j) \\ &= \sum_i \left[ x_i \left\{ \sum_j P(X = x_i \cap Y = y_j) \right\} \right] \\ &= \sum_i x_i P(X = x_i) = E(X). \end{aligned}$$

**Theorem 6.14.** The variance of  $X$  can be regarded as consisting of two parts, the expectation of the conditional variance and the variance of the conditional expectation. Symbolically,

$$V(X) = E[V(X|Y)] + V[E(X|Y)] \quad \dots(6.51)$$

**Proof.**  $E[V(X|Y)] + V[E(X|Y)]$

$$\begin{aligned} &= E\left[E(X^2|Y) - \{E(X|Y)\}^2\right] \\ &\quad + E[\{E(X|Y)\}^2] - [E\{E(X|Y)\}]^2 \\ &= E[E(X^2|Y)] - E[\{E(X|Y)\}^2] \\ &\quad + E[\{E(X|Y)\}^2] - [E\{E(X|Y)\}]^2 \\ &= E[E(X^2|Y)] - [E(X)]^2 \quad \text{(c.f. Theorem 6.13)} \\ &= E\left[\sum_i x_i^2 P(X = x_i | Y = y_j)\right] - [E(X)]^2 \\ &= E\left[\sum_i x_i^2 \frac{P(X = x_i \cap Y = y_j)}{P(Y = y_j)}\right] - [E(X)]^2 \\ &= \sum_j \left\{ \left[ \sum_i x_i^2 \frac{P(X = x_i \cap Y = y_j)}{P(Y = y_j)} \right] P(Y = y_j) \right\} - [E(X)]^2 \\ &= \sum_i \left[ x_i^2 \sum_j P(X = x_i \cap Y = y_j) \right] - [E(X)]^2 \\ &= \sum_i x_i^2 P(X = x_i) - [E(X)]^2 \\ &= E(X^2) - [E(X)]^2 = \text{Var}(X) \end{aligned}$$

Hence the theorem.

**Theorem 6.15.** Let  $A$  and  $B$  be two mutually exclusive events, then

$$E(X|A \cup B) = \frac{P(A)E(X|A) + P(B)E(X|B)}{P(A \cup B)}$$

where by def.,

$$E(X|A) = \frac{1}{P(A)} \sum_{x_i \in A} x_i P(X = x_i)$$

**Proof.**  $E(X|A \cup B) = \frac{1}{P(A \cup B)} \sum_{x_i \in A \cup B} x_i P(X = x_i)$

Since  $A$  and  $B$  are mutually exclusive events,

$$\sum_{x_i \in A \cup B} x_i P(X = x_i) = \sum_{x_i \in A} x_i P(X = x_i) + \sum_{x_i \in B} x_i P(X = x_i)$$

$$\therefore E(X|A \cup B) = \frac{1}{P(A \cup B)} [P(A)E(X|A) + P(B)E(X|B)]$$

Source: NOTES ON PROBABILITY by Greg Lawler. Last Updated: March 21, 2016

### Properties of Conditional Expectation

- $\mathbb{E}[\mathbb{E}[X | \mathcal{G}]] = \mathbb{E}[X]$ .

**Proof.** This is a special case of (16) where  $A = \Omega$ .

- If  $a, b \in \mathbb{R}$ ,  $\mathbb{E}[aX + bY | \mathcal{G}] = a\mathbb{E}[X | \mathcal{G}] + b\mathbb{E}[Y | \mathcal{G}]$ . (This equality and others below are really equalities up an event of probability zero.)

**Proof.** Note that  $a\mathbb{E}[X | \mathcal{G}] + b\mathbb{E}[Y | \mathcal{G}]$  is  $\mathcal{G}$ -measurable. Also, if  $A \in \mathcal{G}$ ,

$$\begin{aligned} \int_A (a\mathbb{E}[X | \mathcal{G}] + b\mathbb{E}[Y | \mathcal{G}]) d\mathbb{P} &= a \int_A \mathbb{E}[X | \mathcal{G}] d\mathbb{P} + b \int_A \mathbb{E}[Y | \mathcal{G}] d\mathbb{P} \\ &= a \int_A X d\mathbb{P} + b \int_A Y d\mathbb{P} \\ &= \int_A (aX + bY) d\mathbb{P}. \end{aligned}$$

The result follows by uniqueness of the conditional expectation.

- If  $X$  is  $\mathcal{G}$ -measurable, then  $\mathbb{E}[X | \mathcal{G}] = X$ .

- If  $\mathcal{G}$  is independent of  $X$ , then  $\mathbb{E}[X | \mathcal{G}] = \mathbb{E}[X]$ . ( $\mathcal{G}$  is independent of  $X$  if  $\mathcal{G}$  is independent of the  $\sigma$ -algebra generated by  $X$ . Equivalently, they are independent if for every  $A \in \mathcal{G}$ ,  $1_A$  is independent of  $X$ .)

**Proof.** The constant random variable  $\mathbb{E}[X]$  is certainly  $\mathcal{G}$ -measurable. Also, if  $A \in \mathcal{G}$ ,

$$\int_A \mathbb{E}[X] d\mathbb{P} = \mathbb{P}(A) \mathbb{E}[X] = \mathbb{E}[1_A] \mathbb{E}[X] = \mathbb{E}[1_A X] = \int_A X d\mathbb{P}.$$

- If  $\mathcal{H} \subset \mathcal{G} \subset \mathcal{F}$  are  $\sigma$ -algebras, then

$$\mathbb{E}[X | \mathcal{H}] = \mathbb{E}[\mathbb{E}[X | \mathcal{G}] | \mathcal{H}]. \quad (17)$$

**Proof.** Clearly,  $\mathbb{E}[\mathbb{E}[X | \mathcal{G}] | \mathcal{H}]$  is  $\mathcal{H}$ -measurable. If  $A \in \mathcal{H}$ , then  $A \in \mathcal{G}$ , and hence

$$\int_A \mathbb{E}[\mathbb{E}[X | \mathcal{G}] | \mathcal{H}] d\mathbb{P} = \int_A \mathbb{E}[X | \mathcal{G}] d\mathbb{P} = \int_A X d\mathbb{P}.$$

- If  $Y$  is  $\mathcal{G}$ -measurable, then

$$\mathbb{E}[XY | \mathcal{G}] = Y \mathbb{E}[X | \mathcal{G}]. \quad (18)$$

**Proof.** Clearly  $Y \mathbb{E}[X | \mathcal{G}]$  is  $\mathcal{G}$ -measurable. We need to show that for every  $A \in \mathcal{G}$ ,

$$\int_A Y \mathbb{E}[X | \mathcal{G}] d\mathbb{P} = \int_A YX d\mathbb{P}. \quad (19)$$

We will first consider the case where  $X, Y \geq 0$ . Note that this implies that  $\mathbb{E}[X | \mathcal{G}] \geq 0$  a.s., since  $\int_A \mathbb{E}[X | \mathcal{G}] d\mathbb{P} = \int_A X d\mathbb{P} \geq 0$  for every  $A \in \mathcal{G}$ . Find simple  $\mathcal{G}$ -measurable random variables  $0 \leq Y_1 \leq Y_2 \leq \dots$  such that  $Y_n \rightarrow Y$ . Then  $Y_n X$  converges monotonically to  $YX$  and  $Y_n \mathbb{E}[X | \mathcal{G}]$  converges monotonically to  $Y \mathbb{E}[X | \mathcal{G}]$ . If  $A \in \mathcal{G}$  and

$$Z = \sum_{j=1}^n c_j 1_{B_j}, \quad B_j \in \mathcal{G},$$

is a  $\mathcal{G}$ -measurable simple random variable,

$$\begin{aligned} \int_A Z \mathbb{E}[X | \mathcal{G}] d\mathbb{P} &= \sum_{j=1}^n c_j \int_A 1_{B_j} \mathbb{E}[X | \mathcal{G}] d\mathbb{P} \\ &= \sum_{j=1}^n c_j \int_{A \cap B_j} \mathbb{E}[X | \mathcal{G}] d\mathbb{P} \\ &= \sum_{j=1}^n c_j \int_{A \cap B_j} X d\mathbb{P} \\ &= \int_A \left[ \sum_{j=1}^n c_j 1_{B_j} \right] X d\mathbb{P} \\ &= \int_A ZX d\mathbb{P}. \end{aligned}$$

Hence (19) holds for simple nonnegative  $Y$  and nonnegative  $X$ , and hence by the monotone convergence theorem it holds for all nonnegative  $Y$  and nonnegative  $X$ . For general  $Y, X$ , we write  $Y = Y^+ - Y^-$ ,  $X = X^+ - X^-$  and use linearity of expectation and conditional expectation.

If  $X, Y$  are random variables and  $X$  is integrable we write  $\mathbb{E}[X | Y]$  for  $\mathbb{E}[X | \sigma(Y)]$ , Here  $\sigma(Y)$  denotes the  $\sigma$ -algebra generated by  $Y$ . Intuitively,  $\mathbb{E}[X | Y]$  is the best guess of  $X$  given the value of  $Y$ . Note that  $\mathbb{E}[X | Y]$  can be written as  $\phi(Y)$  for some function  $\phi$ , i.e., for each possible value of  $Y$  there is a value of  $\mathbb{E}[X | Y]$ . Elementary texts often write this as  $\mathbb{E}[X | Y = y]$  to indicate that for each value of  $y$  there is a value of  $\mathbb{E}[X | Y]$ . Similarly, we can define  $\mathbb{E}[X | Y_1, \dots, Y_n]$ .

### Inequalities Based on Expectation

HOLDER'S INEQUALITY:

$$E|XY| \leq [E|X|^r]^{1/r} \cdot E[|Y|^s]^{1/s} \quad \text{where } r > 0 \text{ \& } \frac{1}{r} + \frac{1}{s} = 1.$$

Proof:

Consider  $\phi(p) = \frac{p^r}{r} + \frac{p^{-s}}{s}$ ;  $0 < p < \infty$

Suppose  $\phi(p)$  has minimum at  $p=1$ , then  $\phi(1) = \frac{1}{r} + \frac{1}{s} = 1$

Let  $p = \frac{a^{1/s}}{b^{1/r}}$ ,  $\therefore a > 0, b > 0$ .

$$\begin{aligned} \text{Then } \phi(p) &= \left[ \frac{a^{1/s}}{b^{1/r}} \right]^r \cdot \frac{1}{r} + \left[ \frac{a^{1/s}}{b^{1/r}} \right]^{-s} \cdot \frac{1}{s} \\ &= \frac{a^{r/s}}{b^{1/r}} + \frac{a^{-1}}{b^{-s/r}} \cdot \frac{1}{s} \\ &= (br)^{-1} \cdot a^{r/s} + (as)^{-1} \cdot b^{s/r} \geq 1 \end{aligned}$$

Multiply by  $ab$ , on both sides

$$r \cdot a^{(r/s)+1} + s \cdot b^{(s/r)+1} \geq ab.$$

$$\Rightarrow r^{-1} a^{\frac{r+s}{s}} + s^{-1} b^{\frac{s+r}{r}} \geq ab \quad \text{--- (1)}$$

As  $\frac{1}{r} + \frac{1}{s} = 1$ ,  $\frac{r+s}{sr} = 1$

$$\Rightarrow \frac{r+s}{r} = s \quad \& \quad \frac{r+s}{s} = r. \quad \text{--- (2)}$$

Using (2), (1) can be written as

$$r^{-1} a^r + s^{-1} b^r \geq ab \quad \text{--- (3)}$$

Let  $a = \frac{|x(\omega)|}{[E|X|^r]^{1/r}}$  and  $b = \frac{|y(\omega)|}{[E|Y|^s]^{1/s}}$

Now (3) becomes,

$$\begin{aligned} r^{-1} \left[ \frac{|x|}{[E|X|^r]^{1/r}} \right]^r + s^{-1} \left[ \frac{|y|}{[E|Y|^s]^{1/s}} \right]^s &\geq \frac{|x| \cdot |y|}{[E|X|^r]^{1/r} \cdot [E|Y|^s]^{1/s}} \\ \Rightarrow \frac{1}{r} \cdot \frac{|x|^r}{E|X|^r} + \frac{1}{s} \cdot \frac{|y|^s}{E|Y|^s} &\geq \frac{|x| \cdot |y|}{[E|X|^r]^{1/r} \cdot [E|Y|^s]^{1/s}} \end{aligned}$$



$$\Rightarrow \frac{\langle |X|^r \cdot E|Y|^s + r|Y|^s E|X|^r \rangle}{r \langle |X|^r \cdot E|Y|^s \rangle} \geq \frac{|X| \cdot |Y|}{[E|X|^r]^{\frac{1}{r}} \cdot [E|Y|^s]^{\frac{1}{s}}}$$

Taking Expectation, we get

$$\frac{r+r}{r \cdot s} \geq \frac{E|X| \cdot E|Y|}{[E|X|^r]^{\frac{1}{r}} \cdot [E|Y|^s]^{\frac{1}{s}}}$$

$$\Rightarrow E|XY| \leq [E|X|^r]^{\frac{1}{r}} \cdot [E|Y|^s]^{\frac{1}{s}} \quad \left[ \begin{array}{l} \bullet \bullet \\ \bullet \end{array} \frac{r+r}{r \cdot s} = 1 \right]$$

### BASIC INEQUALITY:

Let  $X$  be an arbitrary r.v and  $g$  on  $\mathbb{R}$  be a non-negative Borel function. If  $g$  is even and non-decreasing on  $[0, \infty]$ , then for every  $a > 0$

$$\frac{E[g(X)] - g(a)}{a \cdot \sup g(x)} \leq P[|X| \geq a] \leq \frac{E[g(X)]}{g(a)} \quad \text{--- (1)}$$

Proof: - Since,  $g$  is a Borel Borel function on  $\mathbb{R}$ ,  $g(x)$  is measurable function on  $\omega$  and is a r.v. since,  $g$  is a non-negative, its integral exists.

$$\text{Hence, } E[g(X)] = \int_A g(x) + \int_{A^c} g(x)$$

$$\text{where } A = \{|X| \geq a\}$$

On  $A$ , since  $g$  is non-decreasing and even (given),  $g(a) \leq g(x) \leq a \cdot \sup g(x)$ .

$$\text{Hence, } P(A) \cdot g(a) \leq \int_A g(x) \leq a \cdot \sup g(x) \cdot P(A) \quad \text{--- (1)}$$

$$\text{On } A^c, \quad 0 \leq g(x) \leq g(a) \quad \text{and} \\ 0 \leq \int_{A^c} g(x) \leq g(a) P(A^c) \quad \text{--- (2)}$$

Adding ① & ②

$$g(a) \cdot P(A) \leq E[g(x)] \leq a.s. \text{ Sup } g(x) \cdot P(A) + g(a)$$

Consider,

$$E[g(x)] \leq a.s. \text{ Sup } g(x) \cdot P(A) + g(a).$$

$$\Rightarrow E[g(x)] - g(a) \leq a.s. \text{ Sup } g(x) \cdot P(A)$$

$$\Rightarrow \frac{E[g(x)] - g(a)}{a.s. \text{ Sup } g(x)} \leq P(A) \quad \text{--- ③}$$

Consider,

$$g(a) P(A) \leq E[g(x)]$$

$$\Rightarrow P(A) \leq \frac{E[g(x)]}{g(a)} \quad \text{--- ④}$$

Combining ③ & ④

$$\frac{E[g(x)] - g(a)}{a.s. \text{ Sup } g(x)} \leq P(A) \leq \frac{E[g(x)]}{g(a)}$$

$$\text{i.e., } \frac{E[g(x)] - g(a)}{a.s. \text{ Sup } g(x)} \leq P[|x| \geq a] \leq \frac{E[g(x)]}{g(a)}$$

Hence, the Proof.

Corollary:

If we put  $g(x) = |x|^r$ ,  $r > 0$  in the Basic Inequality,

$$\text{We get } \frac{E[|x|^r] - a^r}{a.s. \text{ Sup } |x|^r} \leq P[|x| \geq a] \leq \frac{E[|x|^r]}{a^r}$$

which is called Markov inequality.

If we put  $r=2$  in Markov inequality, we get Chebyshev's inequality.

Convex function:-

Definition:-

Let  $f(x)$  be a real valued convex function defined on an open interval  $I$  (finite or infinite).

Then  $f(x)$  is said to be convex (from below), if for every pair of points  $x, x'$  of  $I$ ,  $\frac{x+x'}{2} \in I$ .

$$f\left(\frac{x+x'}{2}\right) \leq \frac{1}{2}f(x) + \frac{1}{2}f(x')$$

If  $f$  is twice differentiable on  $I$ , convexity is equivalent to  $f''(x) \geq 0$  on  $I$ .

Definition-2:

For every  $x_0 \in I$ , there corresponds a number  $\lambda(x_0)$  such that  $\forall x \in I$ ,  $\lambda(x_0) - (x - x_0) \leq f(x) - f(x_0)$  — (1)

The LHS of (1) is the tangent through  $x_0$ , if it exists. The inequality (1) implies that all the points of the curve  $f(x)$  are above this tangent line.

JENSON'S INEQUALITY:

If  $g$  is continuous and convex function on the interval  $I$ , and  $X$  is a r.v whose values are in  $I$  with probability 1, then

$$E[g(X)] \geq g[E(X)]$$

provided the expectations exist.

Proof:-

To prove  $E(X) \in I$ :-

The various possible cases for  $I$  are:

$$I = (-\infty, \infty); \quad I = (a, \infty); \quad I = (-\infty, b)$$

$$I = (a, b); \quad I = [a, \infty); \quad I = (-\infty, b]$$

and variations of this.

If  $E(X)$  exists, then  $-\infty < E(X) < \infty$

If  $X \geq a$  (a.s), i.e., with probability 1, then  $E(X) \geq a$

If  $X \leq b$  (a.s), then  $E(X) \leq b$ .

Thus  $E(X) \in I$ .

$E(X)$  can be i) either a left end  
or ii) a right end point (if not point) of  $I$  or iii) an interior point of  $I$ .

i) Suppose  $I$  has a left end point 'a', i.e.,  $X \geq a$  a.s.  
Then  $(X-a) \geq 0$  a.s and  $E(X-a) = 0$ .

Thus  $P(X=a) = 1$  (or)  $P[(X-a) = 0] = 1$

$$\begin{aligned} \therefore E[g(X)] &= E[g(a)] \\ &= g(a) \end{aligned} \quad \begin{aligned} & \because g(X) = g(a) \text{ a.s.} \\ & \because g(a) \text{ is a constant} \end{aligned}$$

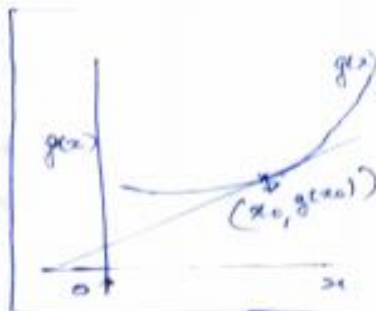
$$= g[E(X)].$$

ii) The result can be proved similarly for right end point 'b'.

iii) Suppose  $E(X) = x_0$  is an interior point of  $I$ .

Let  $ax+b$  pass through the point  $(x_0, g(x_0))$  and let it be below  $g$ .

$$\begin{aligned} E[g(X)] &\geq E[ax+b] = aE[X] + b \\ &= ax_0 + b \\ &= g(x_0) \\ \Rightarrow E[g(X)] &\geq g[E(X)] \end{aligned}$$



Continuous Concave Function:

A continuous function  $g$  is concave on an interval  $I$

if  $(-g)$  is convex.

Corollary to the Jensen's Inequality:

If  $g$  is continuous and concave function on the interval  $I$  and  $X$  is a r.v whose values are in  $I$  with probability 1, then  $E[g(X)] \leq g[E(X)]$  provided the expectations exist.

Results:

1) If  $E(X^2)$  exists then  $E(X^2) \geq [E(X)]^2$

since,  $g(x) = x^2$  is convex function of  $x$  as  $g''(x) = 2 > 0$ .

2) If  $x > 0$  a.s and  $E(x)$  &  $E(1/x)$  exist,

then  $E(1/x) \geq \frac{1}{E(x)}$  since,  $g(x) = 1/x$  is a convex of  $x$  as  $g''(x) = \frac{2}{x^3} > 0$  for  $x > 0$ .

3) If  $x > 0$ , (a.s.), then  $E[x^{1/2}] \leq [E(x)]^{1/2}$

Since  $g(x) = x^{1/2}$ ,  $x > 0$  is a concave function

$$\Rightarrow g''(x) = -\frac{1}{4}x^{-3/2} < 0, \text{ for } x > 0$$

4) If  $x > 0$ , (a.s.) then  $E[\log(x)] \leq \log[E(x)]$ ,

provided the expectations exist, because

$\log x$  is a concave function of  $x$ .

5) Since  $g(x) = E(e^{tx})$  is a convex function of  $x \forall t \neq 0$ ,

If  $E[e^{tx}]$  and  $E(x)$  exist then

$$E[e^{tx}] \geq e^{tE(x)}$$

If  $E(x) = 0$ , then

$$M_x(t) = E(e^{tx}) \geq 1 \quad \forall t.$$

Thus, if  $M_x(t)$  exists, then it has a lower bound 1, provided  $E(x) = 0$ .

This bound is attained at  $t = 0$  and hence,

$M_x(t)$  has a minimum at  $t = 0$ .

6) Let  $f$  and  $g$  be monotone functions on some subset of the real line and  $X$  be a r.v whose range is in the subset (a.s.). If the expectations exist, then

$$E[f(x) \cdot g(x)] \geq E[f(x)] \cdot E[g(x)].$$

(or)

$$E[f(x) \cdot g(x)] \leq E[f(x)] \cdot E[g(x)]$$

According as  $f$  and  $g$  are monotone in the same direction

or in the opposite directions.

MARKOV'S INEQUALITY:

Let  $X$  be a r.v taking non-negative real values  
Then for every  $r \geq 1$ ,

$$P[X \geq r E(X)] \leq \frac{1}{r}$$

ie, If a r.v takes large values with large enough probability, then its average must also be large

Proof:-

Let  $A$  be the event  $X \geq x$ .

$$\begin{aligned} \text{Then } E[X] &= E_A[E(X|A)] \\ &= E[X|A] \cdot P[A] + E[X|A^c] \cdot P[A^c] \end{aligned}$$

Now,  $E[X|A^c] \geq 0$  and  $E[X|A] \geq x$ ,

$$\text{so we get, } P[X \geq x] \leq \frac{E[X]}{x} \quad \text{--- (1)}$$

Let  $x = r \cdot E(X)$ .

$$\begin{aligned} \text{Then (1) becomes,} \\ P[X \geq r E(X)] &\leq \frac{E(X)}{r E(X)} \\ &\leq \frac{1}{r} \end{aligned}$$

Hence, the proof.

Lemma:

Let  $A$  be an event and  $X$  be a r.v.

If  $P[A] \geq 1-p_1-p_2$ , then  $P[P(A|X) > p] \geq 1-p_2$ .

Proof:

Consider the complement of  $A$ ,  $A^c$ .

By assumption,  $P[A^c] \leq 1-p_1+p_2 = (1-p_1)(1-p_2)$

Then,  $E[P(A^c|X)] \leq (1-p_1)(1-p_2)$ .

By Markov's Inequality,

$$P[P(A^c|X) \geq \gamma(1-p_1)(1-p_2)] \leq \frac{1}{\gamma}$$

Let  $\gamma = 1/(1-p_2)$ , then  $P[P(A^c|X) > (1-p_1)] \leq 1-p_2$

Taking the complement of the inner event

we get,  $P[P(A^c|X) < (1-p_1)] \geq 1-p_2$ .

Since,  $P[A^c|X] = 1 - P[A|X]$

we get,  $P[P(A|X) > p] \geq 1-p_2$ .

When we apply this inequality, the  $-p_2$  term is often unimportant.

For example, suppose we know 20% of the Indian students do not get enough exercise.

Let  $X$  be a r.v which is a random school.

Let  $p_1 = p_2 = 10\%$  which implies that in at least 10% of the schools, more than 10% of the students do not get enough exercise